

Setting up Bluetooth on a CCpilot All-Integrated

Submitted by Jochen Wendebaum on Tue, 2015-02-03 09:10

1. Start CC Settings and click telematics
2. Enable bluetooth and select power on at startup
3. Type:
`#modprobe btusb`
4. Now start the service by calling:
`# /etc/init.d/bluetooth start`
Starting Bluetooth...
Bluetooth power set to: ENABLED
5. Run hciconfig to see it is all up and running:
`# hciconfig`
hci0: Type: BR/EDR Bus: USB
BD Address: 00:07:80:5C:09:BA ACL MTU: 310:10 SCO MTU: 64:8
UP RUNNING
RX bytes:340 acl:0 sco:0 events:11 errors:0
TX bytes:38 acl:0 sco:0 commands:11 errors:0
6. Enable some other Bluetooth device and scan for it.
`# hcitool -i hci0 scan`
Scanning ...
E8:15:0E:EF:80:11 Windows Phone

Environment and Versions:

All-Integrated version of CCpilots

Category:

[ARM-Platform](#) ^[1]

[Linux](#) ^[2]

[X86-Platform](#) ^[3]

Source URL: <https://support.crosscontrol.com/kb/setting-bluetooth-ccpilot-all-integrated>

Links

[1] <https://support.crosscontrol.com/kb/arm-platform>

[2] <https://support.crosscontrol.com/kb/linux>

[3] <https://support.crosscontrol.com/kb/x86-platform>